

A simple proof of the representation of bipartite planar graphs as the contact graphs of orthogonal straight line segments [☆]

Jurek Czyzowicz ^{a,*}, Evangelos Kranakis ^{b,1}, Jorge Urrutia ^{c,2}

^a *Département d'Informatique, Université du Québec à Hull, Hull, Québec, Canada J8X 3X7*

^b *Carleton University, School of Computer Science, Ottawa, ON, Canada K1S 5B6*

^c *University of Ottawa, Department of Computer Science, Ottawa, ON, Canada K1N 9B4*

Received 27 June 1997

Communicated by F. Dehne

Keywords: Bipartite; Contact; Line segments; Orthogonal; Planar

Let S be a collection of closed, orthogonal (i.e., vertical and horizontal) straight line segments. The contact graph of a collection S of segments with pairwise disjoint interiors has S as its set of vertices and two segments are adjacent if and only if they touch. De Freysson, de Mendez, and Pach [1] gave a linear algorithm for representing a bipartite planar graph as the contact graph of a set of orthogonal straight line segments. Their method is based on a linear algorithm for constructing bipolar orientations of 2-connected planar graphs.

In this note we give a direct and simple linear time algorithm for representing a bipartite planar graph as the contact graph of a set of orthogonal, closed straight line segments.

Theorem 1. *There is linear time algorithm for representing bipartite planar graphs as the contact graphs of orthogonal, closed straight line segments.*

Proof. We show by induction on the number of vertices of the graph G that the required representation exists. In fact we show that there exists a representation in which the segments representing the vertices of the outer face form a “ladder” in the segment representation of the graph.

To start, let x, y be two adjacent vertices in the outer face; represent x, y by horizontal, vertical segments on the x -, y -axis, respectively (see Fig. 1). Take any node u in the outer face of the graph. Let this vertex be adjacent to d vertices, say $1, 2, \dots, d$. Delete u and all the links adjacent to it. The resulting graph, call it H , is planar bipartite. By the induction hypothesis it has a representation in which the vertices of the outer face form a “ladder” in the segment representation of the graph H . Since the graph is bipartite the segments representing vertices $1, 2, \dots, d$ are either all horizontal or all vertical. Without loss of generality we may assume they all are horizontal. As depicted in Fig. 1 we can extend the segments representing $1, 2, \dots, d$ and add a new vertical segment u in such a way that u touches all segments $1, 2, \dots, d$. The resulting representation clearly satisfies the inductive condition and completes the proof of the theorem. \square

[☆] Research supported in part by NSERC (National Science and Engineering Research Council of Canada) grant.

* Corresponding author. Email: czyzowicz@uqah.quebec.ca.

¹ Email: kranakis@scs.carleton.ca.

² Email: jorge@csi.uottawa.ca.

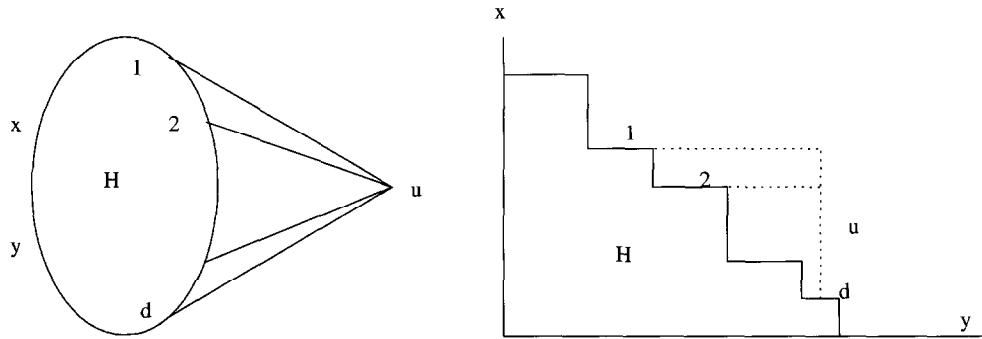


Fig. 1. Inductive construction of the ladder in the outer face of the graph G from the graph H by joining the vertex u . The vertices $1, 2, \dots, d$ are represented by horizontal steps of the ladder.

Reference

- [1] H. de Fraysseix, P.O. de Mendez, J. Pach, A left-first search algorithm for planar graphs, *Discrete Comput. Geom.* 13 (1995) 459–468.